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METHOD AND APPARATUS FOR PERFORMING HIGH-DENSITY DTMF, MF-R1, MF-R2 DETECTION

BACKGROUND OF THE INVENTION

The information age has increased the number of users using data communication systems. Initially, voice was the primary signal carried by phone lines. Next, facsimile (i.e., fax) machines became a popular means for transferring information, though typically restricted to business environments. Recently, with the advent of the Internet, data communications between and among electronic devices has become a common mode of communications for both businesses and individuals. The increase in mode, user group, and usage has driven the telecommunications industry in general, and service providers in particular, to expand capacity. One of the limiting factors of service capacity is the size of detectors for determining dialed digits by various dialing protocols, such as DTMF.

Detection of the dialed digits at the beginning of a phone connection is as old as the PSTN (Public Switched Telephone Network) itself. The requirements are well defined and understood. A current interest is in maximizing the density of DTMF/MF-R1/MF-R2 detection and maintain a high degree of reliability.

In DTMF (Dual-Tone Multi-Frequency) detection, the dialed digits correspond to a *row-frequency* and a *column-frequency*, as shown in Table 1. In MF-R1 (Multi-Frequency, One Row) and MF-R2 (Multi-Frequency, Two Rows) detection, two valid frequencies correspond to a dialed digit, although there are no row or column

5 frequencies as in DTMF. Also note that, in MF-R2, two sets of the frequencies are used depending upon the signaling direction. The MF-R1 and MF-R2 frequencies are respectively shown in Tables 2 and 3.

Table 1

Hz	1209	1336	1447	1633
697	1	2	3	A
770	4	5	6	B
852	7	8	9	C
941	0	0	#	D

10 Table 2

Hz	700	900	1100	1300	1500	1700

Table 3

FWD	1380	1500	1620	1740	1860	1980
BWD	540	660	780	900	1020	1140

15 In each case, a *bandwidth-test* and a *twist-test* must be passed. In the bandwidth-test, frequency deviations greater than 3.5% must be rejected, and frequency deviations less than 1.5% must be declared as valid digits. In the twist-test, powers at the frequencies of interest must be within certain limits with respect to each other. Furthermore, signals from the line that have power levels less than -40dBm0 must be 20 rejected. A condition that is particular to DTMF is falsely detecting digits when there is speech activity on the line. This condition is known as *talk-off*.

One way to increase the density of detectors to allow service providers to support more users is to change (i.e., reduce) the sampling rate of the incoming analog

signal. Changing the sampling rate of the incoming signal for detection is not a new idea, and there are numerous patents on the subject. However, this concept is poorly applied in many cases and there is a great loss of efficiency. For example, the sampling rate of conversion is often implemented through finite impulse response (FIR) multi-rate filters (MRF), which are inefficient in terms of memory and complexity. These are usually implemented by filtering followed by a switch for straight decimation operations. Therefore, the filtering is performed at the higher sampling frequency. A better scheme would be the polyphase implementation of an FIR MRF filter. See P.P. Vaidyanathan, Multi-Rate Systems and Filter Banks, Prentice-Hall, 1993. In this representation, the switching comes first and the FIR coefficients are distributed after the switch. In this way, the filtering is performed at the lower sampling rate.

SUMMARY OF THE INVENTION

Although using FIR MRF filters is a fine idea, it is still inefficient in the context of DTMF due to the aforementioned reasons. For sufficient band isolation, a large number of coefficients might be necessary, and a high number of memory locations are necessary to store the filter histories; thus, a significant computational overhead for filtering is required by the FIR-based MRFs. These shortcomings pose serious problems in high-density applications, since it is desirable to use only the on-chip memory for faster data acquisition and to minimize computational complexity.

In an application, such as telephony, an electrical signal comprising multiple sinusoids that encodes dialed digits is split into multiple subbands. Energies within the subbands are analyzed to determine a presence of sinusoids corresponding to frequencies of dialed digits.

A PS-IIR (power-symmetric infinite impulse response) filter may be employed to split the electrical signal into the subbands. Typically, the electrical signal is split into subbands of 0-1 kHz and 1-2 kHz. Preferably, the PS-IIR filters are implemented in a polyphase form, and all-pass sections composing the PS-IIR filters may be implemented through compact realizations. PS-IIR filters are used to maximize the

density of DTMF/MF-R1/MF-R2 detection and to maintain a high degree of reliability. PS-IIR filters have ideal features for use in detection of dialed digits and can be used for all three detector designs. Techniques employing PS-IIR filters increase density of detectors and provide robust performance in *talk-off* situations in DTMF.

5 The subbands, resulting from whatever band split filter implementation is chosen, are further filtered via a bank of notch filters corresponding to the number of possible relevant frequencies within the respective subbands; the number of relevant frequencies depends on the encoding protocol, DTMF, MF-R1, or MF-R2. The filters are typically notch filters, such as second order infinite impulse response filters. For

10 DTMF detectors, there are four notch filters in the filter banks. For MF-R1 detection, there are two notch filters for the 0-1 kHz subband and four notch filters for the 1-2 kHz subband. For MF-R2 detection, a forward detector comprises six notch filters in the bank of filters for the 1-2 kHz subband; a backward detector comprises (i) a notch filter at 980 Hz and four other notch filters in the bank of filters for the 0-1 kHz subband and

15 (ii) two notch filters in the bank of filters for the 1-2 kHz subband. Further, a preclassifier using frequency estimation may be employed to select only those notch filters corresponding to frequencies determined to be active in the subbands.

 The detectors further comprise detection logic. The detection logic analyzes the subbands to determine whether the sum of the energies exceeds a minimum threshold

20 energy level. The detection logic also performs a twist-test to determine whether the energies in the subbands are within a twist-test threshold. For each subband, the detection logic compares energy levels between the lowest energy output of the notch filters and the input energy to the respective bank of filters. The detection logic aborts detector execution in the event that an energy level test determines a discrepancy with a

25 respective specified criterion and reports valid digits after determining the presence of corresponding valid sinusoids in the electrical signal.

BRIEF DESCRIPTION OF THE DRAWINGS

The foregoing and other objects, features and advantages of the invention will be apparent from the following more particular description of preferred embodiments of the invention, as illustrated in the accompanying drawings in which like reference characters refer to the same parts throughout the different views. The drawings are not necessarily to scale, emphasis instead being placed upon illustrating the principles of the invention.

Fig. 1A is a block diagram of an example telephone network having central offices comprising multi-tone detectors designed according to the principles of the present invention;

Fig. 1B is a block diagram of a media gateway of Fig. 1A employing a multi-tone detector;

Fig. 2 is a block diagram of a circuit board employing the detectors in a central office of Fig. 1A;

Fig. 3 is a block diagram of a DTMF detector executed by a digital processor on a circuit board of Fig. 2;

Fig. 4 is a block diagram of a generic PS-IIR filter executed by the processor of and employed by the DTMF detector of Fig. 3;

Fig. 5 is a block diagram of a compact implementation of a first-order all-pass section employed by the PS-IIR filter of Fig. 4;

Fig. 6 is a plot of frequency responses of (i) a low-pass filter and a high-pass filter composing the band-split filter of Fig. 4 and (ii) spectral lines corresponding to frequencies of sinusoids in the DTMF protocol;

Fig. 7 is a plot of the band-split filter of Fig. 4 and spectral lines of frequencies of sinusoids in the MF-R1 protocol;

Fig. 8 is a plot of the band-split filter of Fig. 4 and spectral lines of frequencies of sinusoids in the MF-R2 protocol;

Fig. 9 is a flow diagram of detection logic for the DTMF protocol employed by the DTMF detector of Fig. 3;

Fig. 10 is a block diagram of an MF-R1 detector employing the PS-IIR band-split filter of Fig. 4;

Fig. 11A-11C are flow diagrams of processing composing (i) MF-R1 detection logic and (ii) MF-R2 forward and backward detection logic employed by the detector of 5 Fig. 10;

Fig. 12 is a block diagram of a forward detector for the MF-R2 protocol employing the PS-IIR band-split filter of Fig. 4 and employing the detection logic of Figs. 11A-11C;

Fig. 13 is a block diagram of a backward detector for the MF-R2 protocol 10 employing the PS-IIR band-split filter of Fig. 4 and employing the detection logic of Figs. 11A-11C;

Fig. 14 is a block diagram of the DTMF detector of Fig. 3 further comprising preclassifiers to improve efficiency; and

Fig. 15 is a flow diagram of an embodiment of the DTMF detection logic of Fig. 15 9 further comprising preclassifier steps to improve efficiency.

DETAILED DESCRIPTION OF THE INVENTION

A description of preferred embodiments of the invention follows.

With the ever-increasing demand to access the telephony network, switching equipment now has to perform DTMF, MF-R1/R2 detection on many more channels. 20 High density detection of dialed digits via DTMF, MF-R1, MF-R2 detection is implemented such that density of the number of channels per digital signal processor (in a digital implementation) is increased.

Density in detector channels is increased in two ways. First, by splitting an input signal into subbands, filters employed by the processor operate at slower sampling rates 25 (i.e., lower bandwidths) and are, therefore, less complex. Further, because the filters operate at slower sampling rates, the processor saves instruction cycles for other operations, including supporting additional detector channels. Second, density is further

improved through the use of a PS-IIR (power symmetric infinite impulse response) filter in the subband splitter.

The PS-IIR filter can be implemented in a minimal memory form by cascading two first-order all-pass filter sections to implement low- and high-pass filters, which 5 compose the PS-IIR filter. In a preferred embodiment, a compact implementation of a first-order all-pass filter section requires only a single coefficient, a single multiplier, and a single unit delay (i.e., storage element). Thus, the PS-IIR filter requires only four storage elements, four coefficients, and very few processor clock cycles.

Banks of notch filters are used to detect the dialed digits encoded in sinusoidal 10 signals at various frequencies. The detector may also comprise at least one preclassifier that performs frequency estimation on the subband signals to determine frequencies of sinusoids in the subbands and enables notch filters within the respective banks of filters corresponding to the frequencies of the sinusoids. In this way, notch filters that do not have an affect on processing of the sinusoids are disabled (i.e., not executed by the 15 processor) to save a significant number of clock cycles.

Detection logic executed by the processor comprises several tests before 20 declaring a valid dialed digit. These tests include an energy level test and a twist-test on the energies in the subbands. The detection logic saves bandwidth in the DSP by exiting upon determining that the input signal does not include a sinusoid-encoded, dialed digit. The detection logic provides support to minimize *talk-off* errors.

Employing the principles of the present invention, it is possible to perform DTMF 25 detection on 1200 or more channels on a single 250 MHZ TMS320C6202 DSP processor. This implementation more than doubles the capacity of preceding solutions. Further, this approach is especially robust against false alarms over speech signals due to *talk-off*.

When implemented in a digital form, the detectors can be changed to support detection of DTMF, MF-R1, or MF-R2 protocol-encoded dialed digits. Each detector type is implemented with similar building blocks (e.g., PS-IIR band split filters), so each type has similar size, accuracy, and speed benefits, as discussed above. Differences

among the different detector types are found in the detector structures and detection logic processes to support the various dialed digit protocols, as discussed in detail below in reference to FIGS. 1-15.

Fig. 1A is a block diagram of a data network 100, which is a subset of a 5 telephony system, in which the present invention may be deployed. Customers 110 communicate to central offices 120. The central offices 120 communicate to one another via inter-central office transmissions 140 via a satellite 130 or via packetized communications across a network, such as an IP (Internet Protocol) network 160 or ATM (Asynchronous Transmission Mode) network 170. Access to the IP network 160 10 and ATM network 170 is through a media gateway 150. The principles of the present invention lend themselves to any system employing tone detection, e.g., touch tone navigation systems.

The customers 110 may communicate to the central offices 120 using voice, 15 telephone, fax, or data accessories (not shown). When connecting to the telephony system, the telephones or other telephony equipment generate sinusoids at specified frequencies according to the DTMF, MF-R1, or MF-R2 protocol used to encode the dialed digits.

Most computer users are familiar with dialed digit tones produced by a computer 20 modem when dialing to a service provider and the dialed digit tones produced by a telephone speaker corresponding to the telephone keypad digits. The dialed digit tones produced and heard comprise two audible frequencies resulting from the speaker acting as a transducer, converting electrical sinusoids to the audible tones. It is these electrical sinusoids that are detected and decoded as dialed digits by equipment in a central office 120. Before discussing details of an embodiment of the equipment employed in a 25 central office 120, a general description of an embodiment employed by a media gateway is presented in Fig. 1B.

Fig. 1B is a block diagram of a media gateway 150 comprising an echo canceler 175, detector 180, and vocoder (i.e., voice-coder) 185. In this example, the media gateway 150 is shown as a network device facilitating voice-over-Internet Protocol

(VOIP). Voice-over-IP is an inexpensive means for communicating across long distances. A voice signal is converted into network packets by the media gateway 150. The network device receiving the IP packet 190 containing the voice signal information converts the data in the network packet 190 back into a voice signal. Radio stations and 5 other broadcast facilities may employ media gateways 150 to broadcast signals over the Internet 160 (Fig. 1A).

The echo canceler 175 removes echoes caused by leakage of electrical signals from hybrids (not shown), having an impedance mismatch, in the media gateway 150 and central office 120, for example. The detector 180 determines sinusoidal tones, 10 indicating dialed digits, received from the central office 120. The detector 180 can be configured to detect DTMF tones, MF-R1 tones, or MF-R2 tones. The vocoder 185 is employed to compress speech signals to increase the bandwidth efficiency. Finally, a packetizer 187 converts the vocoder output to IP packets 190, or other forms of data packets used to transmit data across the data network 100. The IP packets 190 are 15 transmitted across the IP network 160 to an address corresponding to the dialed digits detected by the detector 180. It should be understood that the vocoder 185 can be other forms of encoders, such as video encoders to transmit video streams rather than audio streams. The echo canceler may be of the type described in U.S. Patent Application No. 09/350,497, incorporated herein by reference in its entirety.

20 Fig. 2 is a block diagram of equipment in the central office 120 that is used to detect sinusoids used to encode the dialed digits. The circuit boards 200 comprise an analog-to-digital (A/D) converter 210, digital signal processor (DSP) 220, and external memory 230.

The A/D converter 210 receives an analog signal 205, which is a continuous- 25 time form of an electrical signal, from telephony equipment (not shown) used by the customer 110. The analog signal 205 comprises the sinusoids used to encode the dialed digits. The A/D converter 210 converts the analog signal 205 to a corresponding digital signal 215 at a sampling rate of about 4 kHz.

The DSP 220 comprises internal memory 250, which may include cache, RAM, or ROM, i.e., volatile or non-volatile memory components. The DSP further comprises detectors 240a - 240d (collectively 240). The detectors 240, in the DSP 220 case, are software programs executed by the DSP 220. Because the detectors 240 are

5 implemented in software, they can be quickly changed among DTMF, MF-R1, and MF-R2 detectors to support the dialed digit protocol of the calling device (not shown).

During execution, the detectors 240 access the internal memory 250 for various typical reasons, such as recalling multiplier coefficients or storing intermediate arithmetic results. The detectors 240 may also access external memory 230 for similar 10 or other reasons. Because accessing the external memory 230 typically takes more time than accessing the internal memory 250, initialization parameters for the detectors 240 are generally stored in the external memory 230, while the DSP 220 typically employs the internal memory 250 for real-time memory usages.

Fig. 3 is an embodiment of a DTMF detector 240a executed by the DSP 220 of 15 Fig. 2. The DTMF detector 240a comprises: a PS-IIR band-split filter 300, banks of filters referred to as (i) DTMF low-band notch filters 810a and (ii) DTMF high-band notch filters 810b, respectively, and DTMF detection logic 850a.

The PS-IIR band-split filter 300 receives the digital signal 215 from the A/D converter 210 (Fig. 2). The PS-IIR band-split filter 300 subdivides the digital signal 215 20 into a 2 kHz low-band signal 350, comprising frequencies between 0 Hz and about 1 kHz, and a 2 kHz high-band signal 360, comprising frequencies between about 1 kHz and 2 kHz. Because the 2 kHz low-band signal 350 comprises frequencies between 0 Hz and about 1 kHz, the 2 kHz low-band signal 350 is sometimes referred to as a 0-1 kHz subband. Also, because the 2 kHz high-band signal 360 comprises frequencies between 25 about 1-2 kHz, the 2 kHz high-band signal 360 is sometimes referred to as a 1-2 kHz subband. The low-band signal 350 and high-band signal 360 may also be referred to as simply E_0 and E_1 , respectively, where "E" denotes "energy."

In the DTMF detector 240a, E_0 is processed by the DTMF low-band notch filters 810a, and E_1 is processed by the DTMF high-band notch filters 810b. The DTMF

detection logic 850a processes the outputs of each of the banks of notch filters 810a, 810b. Both the banks of filters 810a, 810b and the detection logic 850a demand less processing time than similar structures processing signals comprising frequency components up to 4 kHz, which is why the PS-IIR band split filter 300 is employed.

5 Fig. 4 is a block diagram of the PS-IIR band-split filter 300. The PS-IIR band-split filter 300 is depicted in polyphase form. An input switch 305 alternates the input between a zero'th first-order all-pass section 310 and a first first-order all-pass section 320. Outputs from first-order all-pass sections 310, 320 are added by an adder 330, producing the 2 kHz low-band signal 350; outputs from the first-order all-pass sections 10 310, 320 are subtracted by a subtractor 340, producing the 2k high-band signal 360.

PS-IIR filters have the following transfer function

$$H_L(z) = \frac{1}{2} \left(A_o(z^2) + z^{-1} A_1(z^2) \right), \text{ where} \quad (1)$$

$$A_i(z^2) = \prod_{j=0}^{p_i-1} \frac{\alpha_{i,j} + z^{-2}}{1 + \alpha_{i,j} z^{-2}}, i = 0, 1 \quad (2)$$

are cascaded, second-order, all-pass sections. Various design methods exist to 15 find the optimal set of $\alpha_{i,j}$ to realize a desired frequency response. For more information regarding finding optimal sets of $\alpha_{i,j}$, see the following references: P.P. Vaidyanathan, Multi-rate Systems and Filter Banks, Prentice-Hall, 1993; O. Tanrikulu and M. Kalkan, "Design and Discrete Re-optimization of All-pass Based Power Symmetric IIR Filters," Electronics Letters, vol. 32, no. 16, pp. 1458-1460, 1996; R. A. Valenzuela and A. G. 20 Constantinides, "Digital Signal Processing Schemes for Efficient Interpolation and Decimation," IEEE Proceedings-G, Circuits Devices and Systems, vol. 130, no. 6, pp. 225-235, 1983; O. Tanrikulu, *Adaptive Algorithms for Accelerated Convergence and Noise Immunity*, Ph.D. Thesis, Imperial College of Science, Technology and Medicine, 1995.

For the problem of detecting dialed digits encoded by sinusoids in an electrical signal, a PS-IIR filter splits the incoming electrical signal into two parallel signal paths at half (i.e., 2 kHz) the input sampling frequency (i.e., 4 kHz). Splitting the incoming signal into two parallel signal paths at half the input sampling frequency is desired to

5 reduce the complexity of the detector and improve detector robustness.

The parallel signal paths separate the row and column frequencies of the DTMF case. Here, $H_l(z)$ is a low-pass filter. Thus, to separate the row and column frequencies, a mirror-image high-pass filter is needed, so, by using a transformation $z \rightarrow -z$, the mirror-image high-pass filter is:

10
$$H_H(z) = \frac{1}{2} \left(A_o(z^2) - z^{-1} A_j(z^2) \right). \quad (3)$$

Since $H_L(z)$ and $H_H(z)$ are structurally similar, the subband splitting operation can be implemented through the polyphase representation of Fig. 4. Note that $A_i(z^2) \rightarrow A_i(z)$ becomes a cascade of first-order all-pass sections. Furthermore, the filtering operations are conducted at the lower sampling rate. And, there is still room

15 for improvement in the implementation of $A_i(z)$ by using a compact realization of all-pass transfer functions rather than a canonical realization. See S. K. Mitra and K. Hirano, "Digital All-pass Networks," IEEE Trans. Circuits Systs., vol. CAS-21, no. 5, pp. 688-700, Sept. 1974.

Fig. 5 is a block diagram of a compact implementation of a first-order all-pass section 400. The first-order all-pass section 400 comprises adders 330, subtractor 340, unit delay 410, and multiplier 420. The unit delay 410 is sometimes referred to as a storage element. The multiplier 420 multiplies a signal by a coefficient, $\alpha_{i,j}$.

An advantage of the implementation in Fig. 5 over less compact implementations is that the first-order all-pass section 400 has only one storage element

25 and a single multiplier. Other implementations that trade storage against the number of additions and multiplications can also be used. See S. K. Mitra and K. Hirano, "Digital All-pass Networks," IEEE Trans. Circuits Systs., vol. CAS-21, no. 5, pp. 688-700, Sept.

1974. Finally, this implementation is structurally passive and lends itself well to
programming on a fixed-point DSP. See O. Tanrikulu, B. Baykal, A.G. Constantinides,
J.A. Chambers and P. A. Naylor, "Finite-precision design and implementation of all-
pass polyphase networks for echo cancellation in sub-bands," ICASSP-95, Detroit,
5 USA, vol., 4, pp. 3039-3042, May 1995.

A cascade of two first-order all-pass sections 400 is employed in each signal
path of the PS-IIR band-split filter 300. In other words, both the zero'th first-order all-
pass section 310 and first first-order all-pass section 320 comprises two first-order all-
pass sections 400, as defined by equation (2) and depicted in Fig. 5.

10 Amplitude spectra of $H_L(z)$ and $H_H(z)$ and the frequency spectral lines
composing the DTMF, MF-R1 and MF-R2 protocols are shown together in Figs. 6 - 8,
respectively. Seeing the relationships among filter frequencies and sinusoid frequencies
is useful for visualizing how the DTMF detector 240a works in detecting the dialed
digits.

15 Fig. 6 is a plot comprising transfer functions of the band-split filter 300 (Fig. 3)
and spectral lines of the frequencies defined in the DTMF protocol. A low-pass filter
transfer function 510 is a frequency response of the low pass filter, $H_L(z)$ of equation
(1), from the PS-IIR band-split filter (Fig. 4). A high-pass filter transfer function 520 is
a frequency response of the high pass filter, $H_H(z)$ of equation (3), from the PS-IIR
20 band-split filter (Fig. 4). The spectral lines 530 correspond to DTMF row/column
frequencies: row frequencies 697 Hz, 770 Hz, 852 Hz, 941 Hz; column frequencies
1209 Hz, 1336 Hz, 1477 Hz, and 1633 Hz.

As suggested by the relationships of the transfer functions 510, 520 and the
spectral lines 530 of the DTMF frequencies, the PS-IIR band-split filter 300 sufficiently
25 isolates the row frequencies from the column frequencies. Here, the PS-IIR band split
filter is designed to isolate the row and column frequencies at 1 kHz, which is
determined by the -3dB point on the transfer functions 510, 520 corresponding to each
of the low- and high-pass filters comprising the PS-IIR filter. However, the row and
column frequencies are not symmetrically distributed with respect to the band-split

filters. Therefore, since the band-split filters are not perfect (i.e., finite stop-band attenuation) in combination with decimation of the 4kHz input signal at 2 kHz (i.e., the input switch 305, Fig. 3), leakage of the energy of the row frequencies adds to the energy observed as column frequencies, and vice-versa. This has an impact on the 5 detector design, which is found in the scale factors, α_r and α_c , having different values.

In summary, the 2 kHz low-band signal 350 (Fig. 3) comprises the row frequencies, namely 697 Hz, 770 Hz, 852 Hz and 941 Hz that are extracted from the digital signal 215 by the low-pass filter of the PS-IIR filter 300. The 2 kHz high-pass signal 360 (Fig. 3) comprises the column frequencies, namely 1209 Hz, 1336 Hz, 1477 10 Hz, and 1633 Hz, that are extracted from the digital signal 215 by the high-pass filter of the PS-IIR band split filter 300. The resulting 2 kHz subband signals are processed separately where advantageous to do so.

Referring again to Fig. 3, the banks of filters 810a, 810b comprise notch filters at row and column frequencies within the respective subbands 350, 360. Outputs from the 15 banks of filters 810a, 810b are received by the DTMF detection logic 850a.

Fig. 9 comprises the DTMF detection logic 850a (Fig. 3). The detector starts in step 905 upon receiving the digital signal 215 (Fig. 3). The PS-IIR band split filter 300 separates the digital signal 215 into energy signals E_0 , E_1 , as described above. The PS-IIR band split filter 300 has a property that the sum of the energies, $E_0 + E_1$, is equal to 20 the energy of the digital signal 215. Thus, a first check is made to determine whether the requisite amount of energy is found in the digital signal 215 received by the DTMF detector 240a (Fig. 3). A signal power level comparator 910 performs the comparison:

$$E_0 + E_1 >? -40\text{dBm0}. \quad (4)$$

If the sum of the energies of E_0 and E_1 are not greater than -40dBm0, the notch 25 filters do not operate on the incoming signals, no DTMF is declared, and processing terminates in step 915. Next, a DTMF twist test 920a is performed, where

$$|E_o - E_1| > ?6dB \quad (5)$$

If the twist test 920a fails, DTMF is not declared, and processing terminates in step 915. Note that this check also prevents speech activity from being falsely detected 5 as DTMF later on, thereby reducing errors due to *talk-offs*. If the twist test 920a does not fail, then processing continues with the execution of the DTMF low-band notch filters 810a.

The notch filter with the lowest output energy is (i) identified at the output of the DTMF low-band notch filters 810a in step 925a and (ii) compared in step 930 to the 10 corresponding input E_o using the comparison formula $E_o > ?E_{o,c}\alpha_c$. This comparison yields whether significant energy is residing in the respective notch bandwidth.

If the result of the comparison is negative, DTMF is not declared and processing terminates in step 915. Thus, the processing for the DTMF high-band notch filter 810b is skipped altogether. Either the signal did not satisfy the bandwidth requirements or it 15 was speech and a *talk-off* signal is presented. If a valid column frequency is detected by the column energy comparitor 930, however, the above procedure is repeated for the DTMF high-band notch filters 810b to determine whether E_i comprises a valid row frequency.

A row minimum selector 935 selects the notch filter with the lowest output 20 energy. The energy of the output of the selected notch filter is compared to the corresponding input E_1 . This comparison yields whether significant energy was residing in that particular notch bandwidth. Similar to the column energy comparator 930, if the row energy comparitor 945 determines that the input energy, E_1 , is greater than $E_{1,r}$, multiplied by the scale factor α_r (i.e., $E_1 > E_{1,r}\alpha_r$), then a valid row frequency is not 25 declared, and the process terminates in step 915. Otherwise, in other words, if valid row and column frequencies are detected, then a valid DTMF is declared for that particular frame of data. As a last protection from false detections, it may be required to detect the

DTMF for a number of frames of data to declare a DTMF is received. Note that the process of Fig. 9 is for a single frame of input data.

It should be noted, and it is also true in MF-R1 and MF-R2, that the thresholds used for input/output energy comparisons are not the same for E_0 and E_1 . The reason is 5 that, as observable in Figs. 6-8, the frequencies of interest and the subband split are not symmetrical with respect to 1000 Hz.

MF-R1 Detection

Fig. 10 is a block diagram for MF-R1 detection. An MF-R1 detector 240b is similar to the DTMF detector 240a (Fig. 3) with two differences. First, the 2 kHz low-10 band signal 350 contains only two frequencies of interest, which can be observed in the frequency plot of Fig. 7.

Referring to Fig. 7, it is observed that the low-pass filter transfer function 510 and the high-pass filter transfer function 520 describing respective filters composing the PS-IIR band split filter 300 are the same as those for the DTMF detector 240a. 15 However, the MF-R1 frequencies 540 fall within the unity gain regions of the two filters 510, 520 in an unequal manner. Specifically, frequencies 700 Hz and 900 Hz are passed by the low-pass filter of the PS-IIR band-split filter 300, while frequencies 1100 Hz, 1300 Hz, 1500 Hz, and 1700 Hz, are passed by the high-pass filter of the PS-IIR band-split filter 300. Sufficient rejection is provided against frequencies not within the 20 respective passbands of the low and high pass filters.

In the MF-R1 protocol, there is no row/column frequency, as in the DTMF protocol. So, when there is an MF-R1 digit, both frequencies can be located in the same subband. Therefore, the detection logic 850b for the MF-R1 signals (i.e., sinusoids) is different from the detection logic 850a (Fig. 3) for the DTMF signals.

25 Fig. 11A is a flow diagram of an MF (MF-R1/R2) detector 850b employed by the MF-R1 detection logic. The MF detector 850b starts in step 905 upon receiving the digital signal 215. The first step of the MF detector 850b, i.e. absolute energy comparison (step 910), is identical to step 910 of the DTMF detector 850a. In the

absolute energy comparison, the lower and upper subband energies E0 and E1 are added together and compared with the absolute threshold (-40 dbm0). If the total energy is greater than -40 dBm0, the MF detector 850b proceeds to the next step, the Twist test (step 933). Here, unlike the DTMF case, there are three possible outcomes, referred to 5 as Case 1, Case 2, and Case 3.

$$\text{Case 1: } 0.14 \leq \frac{E_0}{E_1} \leq 7.08$$

Case 1 corresponds to the upper and lower subband energies being within +/-8.5 dB of each other. In this case, there is a high likelihood that tones are present in both the upper and lower subbands. The MF detector 850b then proceeds exactly as in the 10 case of DTMF, picking one tone from each subband. The bandwidth test is then performed using the lowest output energies from the upper and lower subband notches, as determined in steps 925c, 925b, respectively. If $E_0 > E_{0,1}\alpha_1$ (step 945a) and $E_1 > E_{1,u}\alpha_u$ (step 930a), where $E_{0,1}$ and $E_{1,u}$ are the minimum output energies for the lower and upper subbands respectively, then, in step 950a, the MF detector 850b picks the digit 15 referenced by the two tones.

$$\text{Case 2: } \frac{E_0}{E_1} > 7.08$$

Fig. 11B is a flow diagram of an embodiment of a process of Case 2 of the MF detector. In Case 2, it may be that either (i) there is a twist larger then +8.5dB in the MF signal (with tones present in both subbands) or (ii) all the energy is present in the upper 20 subband. Case 2 then searches for the lowest two output energies, $E_{0,u1}$ (step 925d) and $E_{0,u2}$ (step 925e) from the four upper subband frequencies.

The first test (step 936a) checks to see how noisy the signal is. If

$\frac{E_{0,u1} + E_{0,u2}}{E_0} < 1.35$, the signal is assumed to be relatively noise free. The rationale

behind the test of step 936a is that as the noise level in the signal rises (noise in this case

being any signal that is not an MF frequency tone), the ratio of $\frac{E_{0,u1} + E_{0,u2}}{E_0}$ gets

5 closer and closer to 2.00. For a white noise signal, and using notches of infinitesimal width, the ratio approaches 2.00. On the other hand, with no background noise (i.e. only tonal energy), the ratio approaches 1.00. The test of step 936a is useful for improving the talk-off performance of the MF detector 850b.

The next test (step 939a) checks to see if there are really two distinct tones

10 present in the digital signal 215. If $0.1 < \frac{E_{0,u1}}{E_{0,u2}} < 10.0$, it is likely that there are two

tones in the signal, since the output energies from either of the two notches are good estimators of the energy in the other tone in the subband, given that the signal is relatively noise free.

The last test (steps 945b, 945c) performed is the bandwidth test. If $E_0 > E_{0,u1} \alpha_u$
 15 and $E_0 > E_{0,u2} \alpha_u$, then in step 950b, the MF detector 850b picks the digits referenced by the two tones.

Case 3: $\frac{E_0}{E_1} < 0.14$

Fig. 11C is a flow diagram of an embodiment of a process of Case 3 of the MF detector 215. Case 3 is the last case in the MF detector logic. Again, it can mean that

either all the MF energy is in the lower subband or the twist is greater than -8.5 dB. Since there are only two possible MF frequencies in the lower subband, no search needs to be performed. The output energies $E_{1,10}$ and $E_{1,11}$ are used to carry out a noisy signal test (step 936b), single tone rejection test (step 939b), and bandwidth test (steps 930b, 5 930c) (as in case 2 above). If all the tests pass, the MF detector 850b picks MF digit "1" in step 950c.

MF-R2 Detection

Two detectors for forward and backward frequencies are necessary in the MF-R2 protocol case. The MF-R2 forward frequency detector 240c is depicted in Fig. 12. The 10 MF-R2 backward frequency detector 240d is depicted in Fig. 13.

Referring to Fig. 12, the forward frequencies do not include frequencies below 1 kHz. Therefore, there is no 2 kHz low-band signal 350. The 2 kHz high-band signal 360 comprises six signals, which are filtered by a bank of six notch filters 830a. The forward frequencies are indicated in Fig. 8 as the vertical dashed frequency lines 550. 15 The six MF-R2 forward frequencies, namely 1380 Hz, 1500 Hz, 1620 Hz, 1740 Hz, 1860 Hz, and 1980 Hz are passed by the high-pass filter of the PS-IIR band split filter 300 (Fig. 12), as represented by the high-pass filter transfer function 520.

Fig. 13 is a block diagram of an MF-R2 backward detector 240d. The MF-R2 protocol comprises sinusoids at backward frequencies below 1 kHz and above 1 kHz, so 20 there are two banks of notch filters 830b, 830c, respectively, to filter corresponding sinusoids. The MF-R2 backward detector 240d comprises an extra notch filter 840 to remove 980 Hz from the lower subband.

Referring again to Fig. 8, the MF-R2 backward frequencies 560 are solid frequency spectra lines in the frequency plot. The backward frequencies are 540 Hz, 25 660 Hz, 780 Hz, 900 Hz, 1020 Hz, and 1140 Hz. The backward frequency 1020 Hz is within the transition band of both the low-frequency filter and high-frequency filters of the PS-IIR filter 300 (Fig. 13). Therefore, this frequency shows up in both subbands, E_0

and E_1 . To avoid an extra signal from causing an error, the notch filter 840 is used to remove the 1020 Hz frequency from the lower subband.

The DTMF detector 240a passes the Net-4 European tests with no failures.

Talk-off tests for the entire Bell-Core test signals yield only 5 *talk-off* cases compared to 5 an existing DTMF detector, which is one-fifth the density and fails around 250 times. Existing systems provide approximately 300 channels per circuit board, whereas a system employing the filters, etc., described above provides 1500 channels. Through another level of optimization, 2500 channels per board are possible, as described below in reference to Figs. 14-15.

10 Since there are eight notch filters but only two signals being detected, there are six notch filters needlessly executing instructions, thus wasting execution cycles. Saving the execution cycles allows for an increase in the number of detectors that may be executed by the DSP 220 (Fig. 2). To determine which two notch filters are necessary for detecting sinusoids present in the digital signal 215 corresponding to the 15 analog signal 205, a preclassifier may be employed. The preclassifier performs frequency estimation to select which two notch filters should be used. Though requiring execution cycles, the preclassifier saves six of eight notch filters from wasting execution cycles, thus increasing the number of detectors per board from 1500 to 2500.

Fig. 14 is a modified DTMF detector 240e. The modified DTMF detector 240e 20 comprises preclassifiers 805a and 805b. The preclassifiers 805a, 805b receive respective subbands 350, 360 from the PS-IIR band split filter 300. Each preclassifier 805a, 805b performs frequency estimation to determine which notch filter(s) within the respective banks of notch filters 810a, 810b should be executed to determine whether the DTMF signals are present.

25 Fig. 15 is a flow diagram of an embodiment of a modified DTMF detection logic 850c employed by the modified DTMF detector 240e. The modified DTMF detection logic 850c comprises the preclassifiers 805a, 805b and indicates their relative positions within the process. Other than the preclassifiers 805a, 805b, the modified DTMF detection logic 850c is the same as the DTMF detection logic 850a described in Fig. 9.

The signaling detectors described herein take advantage of subband decomposition using IIR filter-banks. This brings high computational efficiency and low memory costs which are useful in high density applications, such as DTMF detection, and increases the number of channels, or customers, a service provider can support from a central office.

Equivalents:

The principles of the present invention allow for the embodiments described herein to be expanded to other forms of encoding protocols, such as protocols comprising three, four, or more sinusoids. Band-reject and band-pass filters rather than strictly low-pass and high-pass filters to produce corresponding three, four, or more subdivisions may be employed; a similar set of filters may be employed in an alternative embodiment of the PS-IIR band-split filter 300 (Fig. 3).

The detection logic, filters, and other aspects of the processes and functions described herein are not restricted to any particular software language or data structure. The hardware depicted is merely exemplary. Alternative processors, from analog circuits to ASICs (application specific integrated circuits), may be employed.

Although subband filtering is employed to dissect the time domain signal by determining a frequency domain signal equivalent, alternative transforms yielding a one-to-one mapping between the time and frequency domains may be employed.

Examples of alternative transforms include: DFT (discrete Fourier transform), DHT (discrete Hartley transform), DCT (discrete Cosine transform), Wavelets, etc. Typical processing following the alternative transforms may vary according to the respective transforms but are still within the scope of the principles of the present invention.

While this invention has been particularly shown and described with references to preferred embodiments thereof, it will be understood by those skilled in the art that various changes in form and details may be made therein without departing from the scope of the invention encompassed by the appended claims.